

## In the Claims

1 1. (currently amended) A method for detecting symbols of a modulated  
2 signal received via channels of a wireless communications system,  
3 comprising:  
4 obtaining an initial estimate of a symbol transmitted via the channels  
5 from a previous channel estimate and a received symbol;  
6 updating the channel estimate;  
7 optimizing ~~the~~ a next estimate of the transmitted symbol which  
8 maximizes an expectation of a log likelihood function by averaging a  
9 logarithm of a likelihood function over unknown parameters  $h$  of the  
10 channels;  
11 quantizing the next estimate of the transmitted symbol;  
12 comparing the quantized next estimate of the transmitted symbol with  
13 the ~~previous~~ initial estimate of the transmitted symbol to determine if the  
14 ~~previous~~ initial estimate of the transmitted symbol and the quantized next  
15 estimate of the transmitted symbol have converged; and otherwise  
16 inputting the quantized next estimate of the transmitted symbol as the  
17 initial estimate of the transmitted symbol; and  
18 repeating the updating, the optimizing, the quantizing, and the  
19 comparing until the ~~previous~~ initial estimate of the transmitted symbol and  
20 the quantized next estimate of the transmitted symbol converge.

1 2. (currently amended) The method of claim 1 wherein the modulated signal  
2 is a MPSK modulated signal having a positive constant equivalent to an  
3 energy of the modulated signal, and using only phase information during the  
4 updating.

1 3. (currently amended) The method of claim 1 wherein the comparing  
2 further comprises:  
3       subtracting the ~~previous~~ initial estimate of the transmitted symbol  
4 from the quantized next estimate of the transmitted symbol to obtain a  
5 difference; and  
6       determining that the ~~previous~~ initial estimate and the quantized next  
7 estimate have converged when an absolute value of the difference is less  
8 than a predetermined threshold.

1 4. (currently amended) The method of claim 1 further comprising:  
2       obtaining the initial estimate of the transmitted symbol from the  
3 channel estimate of a pilot symbol received via the channels.

1 5. (currently amended) The method of claim 1 further comprising:  
2       obtaining the initial estimate of the transmitted symbol from the  
3 channel estimate of a previously received symbol.

1 6. (currently amended) The method of claim 1 wherein the optimizing  
2 further comprises:  
3       using only a fast Fourier transform matrix, the received ~~signal~~ symbol,  
4 and the previous channel estimate .

7. (currently amended) The method of claim 1 wherein the next estimate of the transmitted symbol is quantized according to ~~the signal constellation~~ a constellation of the received signal.

8. (currently amended) The method of claim 1 further comprising:  
determining a posterior covariance matrix  $\Xi_p$   $\hat{\Sigma}_p$  of the channels using a FFT matrix  $\mathbf{W}$ , the ~~previous~~ initial estimate of the transmitted symbol  $\mathbf{X}_p$ , the received symbol  $\mathbf{Y}$ , and a Gaussian noise variance  $\sigma^2$  as

$$\hat{\Sigma}_p = (\mathbf{W}^H \mathbf{X}_p^H \mathbf{X}_p \mathbf{W} / \sigma^2)^{-1},$$

determining a posterior mean  $\hat{h}_p$  of a channel impulse response as

$$\hat{h}_p = \hat{\Sigma}_p (\mathbf{W}^H \mathbf{X}_p^H \mathbf{Y} / \sigma^2);$$

determining a channel update coefficients matrix  $\mathbf{C}$  for recovering the next estimate of the transmitted symbol; and

applying the coefficient matrix  $\mathbf{C}$  to the posterior mean  $\hat{h}_p$ , the FFT matrix  $\mathbf{W}$ , and the received ~~signal~~ symbol  $\mathbf{Y}$  according to

$$\tilde{\mathbf{X}}_{p+1} = \mathbf{C}^{-1} (\hat{h}_p^H \mathbf{W}^H \mathbf{Y})^T \text{ to optimize the next estimate of the } \underline{\text{transmitted symbol}}$$

$$\mathbf{X}_{p+1} \underline{\tilde{\mathbf{X}}_{p+1}}.$$

9. (currently amended) The method of claim 1 further comprising:  
determining a posterior covariance matrix  $\Xi_p$   $\hat{\Sigma}_p$  of the channels using a FFT matrix  $\mathbf{W}$ , the previous estimate of the transmitted symbol  $\mathbf{X}_p$ , a channel convergence matrix  $\Sigma^{-1}$ , and a Gaussian noise variance  $\sigma^2$  as

$$\hat{\Sigma}_p = (\mathbf{W}^H \mathbf{X}_p^H \mathbf{X}_p \mathbf{W} / \sigma^2 + \Sigma^{-1})^{-1};$$

6 determining a posterior mean  $\hat{h}_p$  of a channel impulse response as  
7  $\hat{h}_p = \hat{\Sigma}_p (\mathbf{W}^H \mathbf{X}_p^H \mathbf{Y} / \sigma^2 + \Sigma^{-1} E\{h\})$ , where the received symbol is  $\mathbf{Y}$ , and  $E\{h\}$  is  
8 a channel impulse response;  
9 determining a channel update coefficients matrix  $\mathbf{C}$  for recovering the  
10 next estimate of the transmitted symbol; and  
11 applying the coefficient matrix  $\mathbf{C}$  to the posterior mean  $\hat{h}_p$ , the FFT  
12 matrix  $\mathbf{W}$ , and the received ~~signal~~ symbol  $\mathbf{Y}$  according to  
13  $\tilde{\mathbf{X}}_{p+1} = \mathbf{C}^{-1} (\hat{h}_p^H \mathbf{W}^H \mathbf{Y})^T$  to optimize the next estimate of the transmitted symbol  
14  ~~$\mathbf{X}_{p+1}$~~   $\tilde{\mathbf{X}}_{p+1}$ .

1 10. (cancelled)

1 11. (original) The method of claim 1 further comprising:  
2 modulating the signal using orthogonal frequency division  
3 multiplexing.

1 12. (currently amended) A system for detecting symbols of a modulated  
2 signal received via a plurality of channel of a wireless communications  
3 system, comprising:  
4 means for obtaining an initial estimate of a symbol transmitted via the  
5 channels;  
6 means for updating the channel estimate;  
7 means for optimizing a next estimate of the transmitted symbol which  
8 maximizes an expectation of a log likelihood function by averaging a  
9 logarithm of a likelihood function over unknown parameters  $h$  of the

10 channels;  
11 means for quantizing the next estimate of the transmitted symbol;  
12 means for comparing the quantized next estimate of the transmitted  
13 symbol with the previous estimate of the transmitted symbol to determine if  
14 the ~~previous~~ initial estimate and the quantized next estimate have converged;  
15 and otherwise  
16 means for making the quantized next estimate of the transmitted  
17 symbol an input for a next iteration; and  
18 means for repeating the updating, the optimizing, the quantizing, and  
19 comparing until the ~~previous~~ initial estimate of the transmitted symbol and  
20 the quantized next estimate of the transmitted symbol converge.

1 13. (currently amended) The system of claim 12 wherein the modulated  
2 signal is a ~~MPSK~~ multiple phase shift keying modulated signal having a  
3 positive constant equivalent to an energy of the modulated signal, and using  
4 only phase information during the updating.

1 14. (currently amended) The system of claim 12 further comprising:  
2 means for subtracting the ~~previous~~ initial estimate of the transmitted  
3 symbol from the quantized next estimate of the transmitted symbol to obtain  
4 a difference; and  
5 means for determining that the ~~previous~~ initial estimate and the next  
6 estimate have converged when an absolute value of the difference is less  
7 than a predetermined threshold.

1 15. (currently amended) The system of claim 12 wherein the initial estimate  
2 of the transmitted symbol is obtained from a pilot symbol received via the  
3 channels.

1 16. (currently amended) The system of claim 12 wherein the initial estimate  
2 of the transmitted symbol is obtained from a channel estimate from ~~the~~  
3 ~~previous~~ a previously received symbol.

1 17. (currently amended) The system of claim 12 further comprising:  
2 means for determining a posterior covariance matrix  $\Sigma_p$   $\hat{\Sigma}_p$  of the  
3 channels using a FFT matrix  $\mathbf{W}$ , the initial estimate of the ~~previous~~  
4 transmitted symbol  $\mathbf{X}_p$ , the received symbol  $\mathbf{Y}$ , and a Gaussian noise  
5 variance  $\sigma^2$  as  $\hat{\Sigma}_p = (\mathbf{W}^H \mathbf{X}_p^H \mathbf{X}_p \mathbf{W} / \sigma^2)^{-1}$ ,  
6 means for determining a posterior mean  $\hat{h}_p$  of the channel impulse  
7 response as  $\hat{h}_p = \hat{\Sigma}_p (\mathbf{W}^H \mathbf{X}_p^H \mathbf{Y} / \sigma^2)$ ;  
8 means for determining a channel update coefficients matrix  $\mathbf{C}$  for  
9 recovering the next estimate of the ~~next~~ transmitted symbol; and  
10 means for applying the coefficient matrix  $\mathbf{C}$  to the posterior mean  $\hat{h}_p$ ,  
11 the FFT matrix  $\mathbf{W}$ , and the received ~~signal~~ symbol  $\mathbf{Y}$  according to  
12  $\tilde{\mathbf{X}}_{p+1} = \mathbf{C}^{-1} (\hat{h}_p^H \mathbf{W}^H \mathbf{Y})^T$  to maximize the next estimate of the ~~next~~ symbol  $\mathbf{X}_{p+1}$   
13  $\tilde{\mathbf{X}}_{p+1}$ .

1 18. (currently amended) The system of claim 12 further comprising:  
2 means for determining a posterior covariance matrix  $\underline{\Sigma}_p$   $\hat{\Sigma}_p$  of the  
3 channels using the FFT matrix  $\mathbf{W}$ , the initial estimate of the ~~previous~~  
4 transmitted symbol  $\mathbf{X}_p$ , a ~~channels~~ channel convergence matrix  $\Sigma^{-1}$ , and a  
5 Gaussian noise variance  $\sigma^2$  as  $\hat{\Sigma}_p = (\mathbf{W}^H \mathbf{X}_p^H \mathbf{X}_p \mathbf{W} / \sigma^2 + \Sigma^{-1})^{-1}$ ;  
6 means for determining a posterior mean  $\underline{\hat{h}}_p$  of ~~the channels~~ a channel  
7 impulse response as  $\underline{\hat{h}}_p = \hat{\Sigma}_p (\mathbf{W}^H \mathbf{X}_p^H \mathbf{Y} / \sigma^2 + \Sigma^{-1} E\{\underline{h}\})$ , where the received  
8 symbol is  $\mathbf{Y}$  and  $E\{\underline{h}\}$  is a channel impulse response;  
9 means for determining a channel update coefficients matrix  $\mathbf{C}$  for  
10 recovering the estimate of the next transmitted symbol; and  
11 means for applying the coefficient matrix  $\mathbf{C}$  to the posterior mean  $\underline{\hat{h}}_p$ ,  
12 the FFT matrix  $\mathbf{W}$ , and the received ~~signal~~ symbol  $\mathbf{Y}$  according to  
13  $\underline{\tilde{X}}_{p+1} = \mathbf{C}^{-1} (\underline{\hat{h}}_p^H \mathbf{W}^H \mathbf{Y})^T$  to maximize the next estimate of the ~~next~~ symbol  ~~$\mathbf{X}_{p+1}$~~   
14  $\underline{\tilde{X}}_{p+1}$ .

1 19. (cancelled)

1 20. (original) The system of claim 12 wherein the signal is modulated using  
2 orthogonal frequency division multiplexing.